

Center of Mass in Two Dimensions

The center of mass is also known as the center of gravity if the object is in a uniform gravitational field. If the object has uniform density, the center of mass is the geometric center of the object, which is called the centroid. [Figure](https://cnx.org/contents/Q_0pMyhf@3/Calculating-Centers-of-Mass-an#CNX_Calc_Figure_15_06_001) shows a point P as the center of mass of a lamina. The lamina is perfectly balanced about its center of mass.

$$
\text{Mass} = \rho A = \rho \int_R dA = \int_R \rho \, dA. \qquad \text{Constant density}
$$

Definition of Mass of a Planar Lamina of Variable Density

If ρ is a continuous density function on the lamina corresponding to a plane region R , then the mass m of the lamina is given by

$$
m = \iint_{R} \rho(x, y) dA.
$$

Variable density

EXENUELE 1

Finding the Mass of a Planar Lamina

Find the mass of the triangular lamina with vertices $(0, 0)$, $(0, 3)$, and $(2, 3)$, given that the density at (x, y) is $\rho(x, y) = 2x + y$.

Moments and Center of Mass of a Variable Density Planar Lamina Let ρ be a continuous density function on the planar lamina R. The moments of mass with respect to the x - and y -axes are

$$
M_x = \int_R \int y \rho(x, y) \, dA
$$

and

$$
M_{y} = \iint_{R} x \rho(x, y) \, dA.
$$

If m is the mass of the lamina, then the **center of mass** is

$$
(\overline{x},\overline{y})=\bigg(\frac{M_{y}}{m},\frac{M_{x}}{m}\bigg).
$$

If R represents a simple plane region rather than a lamina, then the point (\bar{x}, \bar{y}) is called the **centroid** of the region.

EXAMPLE 3 **Finding the Center of Mass**

:... > See LarsonCalculus.com for an interactive version of this type of example.

Find the center of mass of the lamina corresponding to the parabolic region

 $0 \le y \le 4 - x^2$ Parabolic region

where the density at the point (x, y) is proportional to the distance between (x, y) and the x -axis, as shown in Figure 14.38.

Definition of Triple Integral

If f is continuous over a bounded solid region Q , then the **triple integral of f** over Q is defined as

$$
\iiint_{O} f(x, y, z) dV = \lim_{\|\Delta\| \to 0} \sum_{i=1}^{n} f(x_i, y_i, z_i) \Delta V_i
$$

provided the limit exists. The volume of the solid region Q is given by

Volume of
$$
Q = \iiint_Q dV
$$
.

 \sim y

THEOREM 14.4 Evaluation by Iterated Integrals Let f be continuous on a solid region Q defined by

 $a \leq x \leq b$, $h_1(x) \le y \le h_2(x),$ $g_1(x, y) \le z \le g_2(x, y)$

where h_1 , h_2 , g_1 , and g_2 are continuous functions. Then,

$$
\iiint_{Q} f(x, y, z) dV = \int_{a}^{b} \int_{h_{1}(x)}^{h_{2}(x)} \int_{g_{1}(x, y)}^{g_{2}(x, y)} f(x, y, z) dz dy dx.
$$

EXAMPLE 1

Evaluating a Triple Iterated Integral

 ~ 2.4

Evaluate the triple iterated integral

$$
\int_0^2 \int_0^x \int_0^{x+y} e^x (y+2z) \, dz \, dy \, dx.
$$

EXAMPLE 4 **Determining the Limits of Integration**

Set up a triple integral for the volume of each solid region.

- **a.** The region in the first octant bounded above by the cylinder $z = 1 y^2$ and lying between the vertical planes $x + y = 1$ and $x + y = 3$
- **b.** The upper hemisphere $z = \sqrt{1 x^2 y^2}$
- c. The region bounded below by the paraboloid $z = x^2 + y^2$ and above by the sphere $x^2 + y^2 + z^2 = 6$

