

$$\text{Force} = (\text{mass})(\text{acceleration}).$$

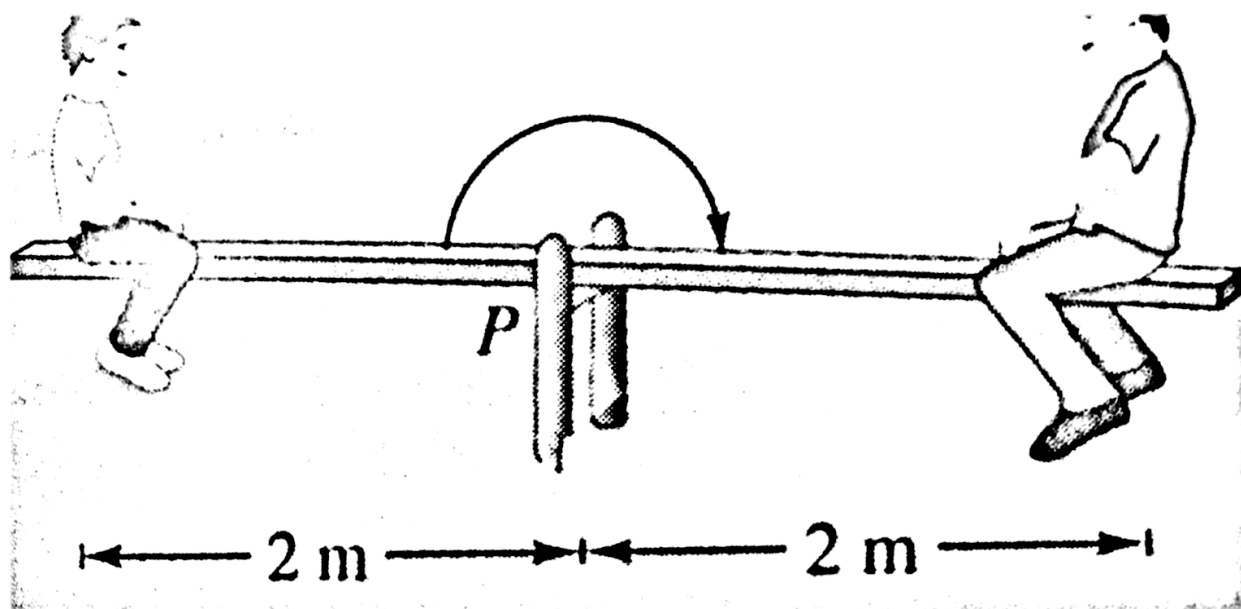
Below lists some commonly used measures of mass and force, together with conversion factors.

System of Measurement	Measure of Mass	Measure of Force
U.S.	Slug	Pound = (slug)(ft/sec ²)
International	Kilogram	Newton = (kilogram)(m/sec ²)
C-G-S	Gram	Dyne = (gram)(cm/sec ²)
Conversions:		
1 pound = 4.448 newtons	1 slug = 14.59 kilograms	
1 newton = 0.2248 pound	1 kilogram = 0.06852 slug	
1 dyne = 0.00002248 pound	1 gram = 0.00006852 slug	
1 dyne = 0.00001 newton	1 foot = 0.3048 meter	

EXAMPLE 1

Mass on the Surface of Earth

Find the mass (in slugs) of an object whose weight at sea level is 1 pound.



Moments and Center of Mass: One-Dimensional System

Let the point masses m_1, m_2, \dots, m_n be located at x_1, x_2, \dots, x_n .

1. The moment about the origin is

$$M_0 = m_1x_1 + m_2x_2 + \dots + m_nx_n.$$

2. The center of mass is

$$\bar{x} = \frac{M_0}{m}$$

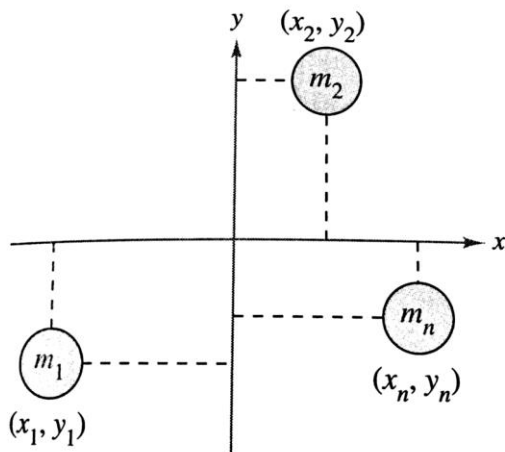
where $m = m_1 + m_2 + \dots + m_n$ is the total mass of the system.

EXAMPLE 2 The Center of Mass of a Linear System

Find the center of mass of the linear system shown in Figure 7.55.



Figure 7.55



In a two-dimensional system, there is a moment about the y -axis M_y and a moment about the x -axis M_x .

Figure 7.56

Moment and Center of Mass: Two-Dimensional System

Let the point masses m_1, m_2, \dots, m_n be located at $(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)$.

1. The moment about the y -axis is

$$M_y = m_1x_1 + m_2x_2 + \dots + m_nx_n.$$

2. The moment about the x -axis is

$$M_x = m_1y_1 + m_2y_2 + \dots + m_ny_n.$$

3. The center of mass (\bar{x}, \bar{y}) (or center of gravity) is

$$\bar{x} = \frac{M_y}{m} \quad \text{and} \quad \bar{y} = \frac{M_x}{m}$$

where

$$m = m_1 + m_2 + \dots + m_n$$

is the total mass of the system.

EXAMPLE 3**The Center of Mass of a Two-Dimensional System**

Find the center of mass of a system of point masses $m_1 = 6$, $m_2 = 3$, $m_3 = 2$, and $m_4 = 9$, located at

$$(3, -2), (0, 0), (-5, 3), \text{ and } (4, 2)$$

as shown in Figure 7.57.

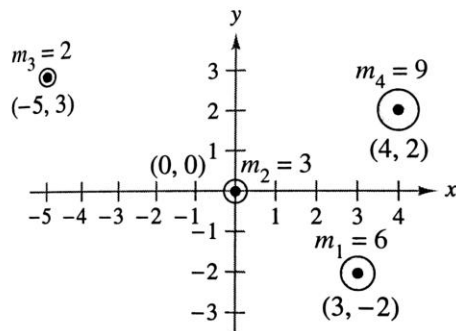
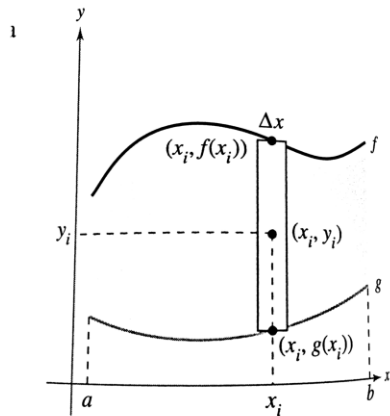


Figure 7.57



Planar lamina of uniform density ρ
Figure 7.59

Moments and Center of Mass of a Planar Lamina

Let f and g be continuous functions such that $f(x) \geq g(x)$ on $[a, b]$, and consider the planar lamina of uniform density ρ bounded by the graphs of $y = f(x)$, $y = g(x)$, and $a \leq x \leq b$.

1. The moments about the x - and y -axes are

$$M_x = \rho \int_a^b \left[\frac{f(x) + g(x)}{2} \right] [f(x) - g(x)] dx$$

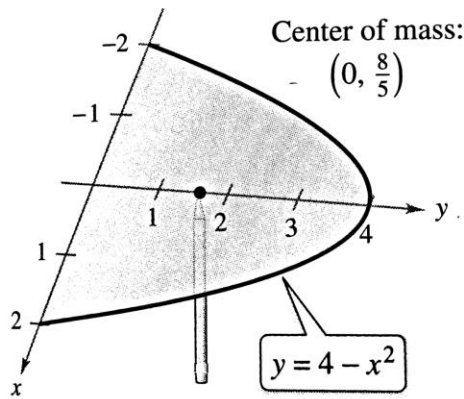
$$M_y = \rho \int_a^b x[f(x) - g(x)] dx.$$

2. The center of mass (\bar{x}, \bar{y}) is given by $\bar{x} = \frac{M_y}{m}$ and $\bar{y} = \frac{M_x}{m}$, where $m = \rho \int_a^b [f(x) - g(x)] dx$ is the mass of the lamina.

EXAMPLE 4**The Center of Mass of a Planar Lamina**

•••▶ See LarsonCalculus.com for an interactive version of this type of example.

Find the center of mass of the lamina of uniform density ρ bounded by the graph of $f(x) = 4 - x^2$ and the x -axis.



The center of mass is the balancing point.

Figure 7.60

EXAMPLE 5 The Centroid of a Plane Region

Find the centroid of the region bounded by the graphs of $f(x) = 4 - x^2$ and $g(x) = x + 2$.

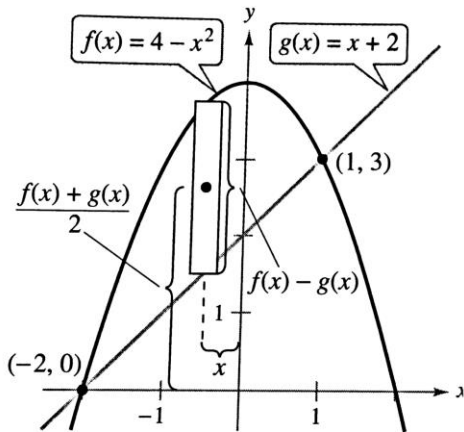
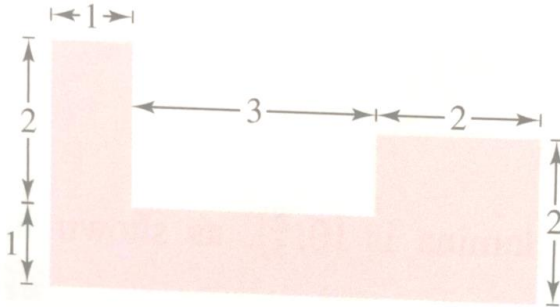


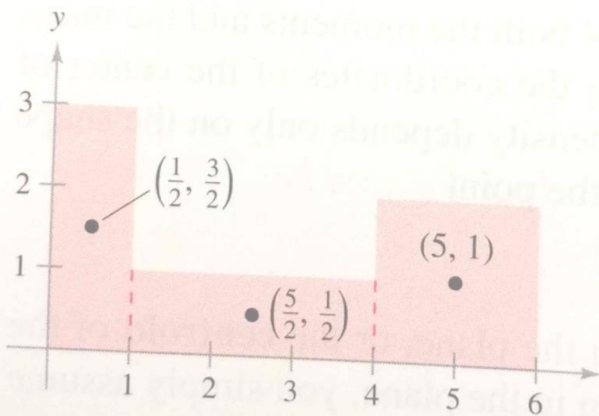
Figure 7.61

EXAMPLE 6**The Centroid of a Simple Plane Region**

Find the centroid of the region shown in Figure 7.62(a).



(a) Original region



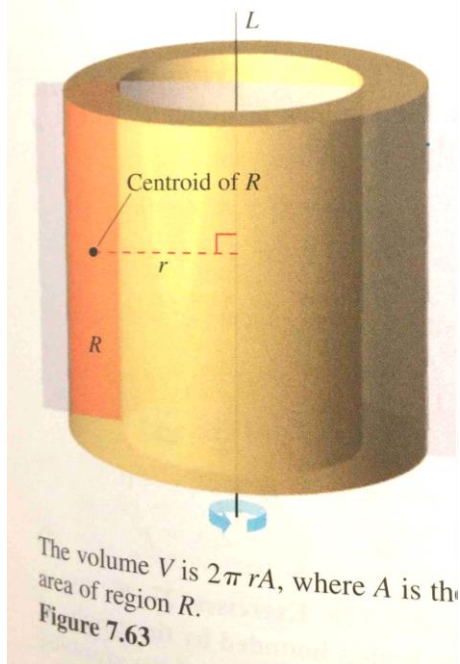
(b) The centroids of the three rectangles
Figure 7.62

THEOREM 7.1 The Theorem of Pappus

Let R be a region in a plane and let L be a line in the same plane such that L does not intersect the interior of R , as shown in Figure 7.63. If r is the distance between the centroid of R and the line, then the volume V of the solid of revolution formed by revolving R about the line is

$$V = 2\pi rA$$

where A is the area of R . (Note that $2\pi r$ is the distance traveled by the centroid as the region is revolved about the line.)



EXAMPLE 7 Finding Volume by the Theorem of Pappus

Find the volume of the torus shown in Figure 7.64(a), which was formed by revolving the circular region bounded by

$$(x - 2)^2 + y^2 = 1$$

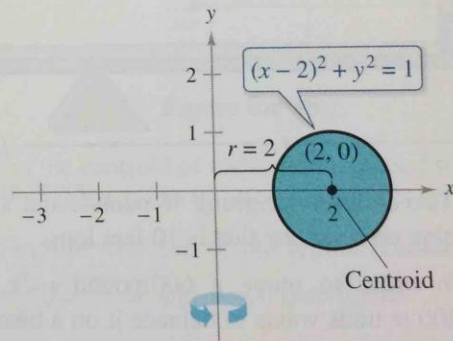
about the y -axis, as shown in Figure 7.64(b).



Torus

(a)

Figure 7.64



(b)